L Number	Hits	Search Text	DB	Time stamp
1	322186	robot and (cd medium diskette zip tape) and operational arc	USPAT;	2001/09/10 13:06
			US-PGPUB;	
			ЕРО; ЈРО;	
			DERWENT;	
			IBM TDB	
2	795861	software program instruction command and two adj state	USPAT;	2001/09/10 13:09
	.,,,,,	,	US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
			IBM TDB	
3	22567	(robot and (cd medium diskette zip tape) and operational arc) and	USPAT;	2001/09/10 13:09
	22307	(software program instruction command and two adj state)	US-PGPUB;	
		(bottware program mended of conditions and two and state)	ЕРО; ЛРО;	
			DERWENT;	
			IBM TDB	
4	448283	weighting coefficient	USPAT;	2001/09/10 13:10
4	446263	weighting coefficient	US-PGPUB;	2001/03/10 13:10
I			ЕРО; ЛРО;	
			DERWENT;	
		·	,	
			IBM TDB	2001/00/10 12:11
5	3807	((robot and (cd medium diskette zip tape) and operational arc) and	USPAT;	2001/09/10 13:11
Ì		(software program instruction command and two adj state)) and	US-PGPUB;	
. !		(weighting coefficient)	ЕРО; ЛРО;	
			DERWENT;	
1			IBM TDB	
7	3	(((robot and (cd medium diskette zip tape) and operational arc) and	USPAT;	2001/09/10 13:12
		(software program instruction command and two adj state)) and	US-PGPUB;	
		(weighting coefficient)) and (predetermin\$3 adj probability)	ЕРО; ЛРО;	
			DERWENT;	
			IBM TDB	
6	467	predetermin\$3 adj probability	USPAT;	2001/09/10 13:41
Ĭ		, in the second	US-PGPUB,	
			ЕРО; ЛРО;	
			DERWENT,	
			IBM TDB	
8	371300	(((robot and (cd medium diskette zip tape) and operational arc) and	USPAT;	2001/09/10 13:43
	371300	(software program instruction command and two adj state)) and	US-PGPUB;	
		(weighting coefficient)) and state model	ЕРО; ЛРО;	
		(weighting coefficient)) and state model	DERWENT;	
			IBM TDB	
0	52	(((robot and (cd medium diskette zip tape) and operational arc) and	USPAT;	2001/09/10 13:43
9	32	((Tobot and (et methan disacte zip tape) and operational are) and (software program instruction command and two adj state)) and	US-PGPUB;	2001/07/10 13:13
		(weighting coefficient)) and state adj model	ЕРО; ЛРО;	
		(Weighting coefficient)) and state adj moder	DERWENT;	
ļ			IBM TDB	
		1 14 1 62 1 1 1 1 1 1 1	1	2001/09/10 13:59
10	0	robot and medium same program and predetermin\$3 adj operartion and	USPAT;	2001/09/10 13.39
		two adj state	US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
			IBM TDB	2001/00/10 14 00
11	0	robot and medium same program and predetermin\$3 adj operartion	USPAT;	2001/09/10 14:00
			US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
			IBM TDB	
12	0	robot and medium and predetermin\$3 adj operartion	USPAT;	2001/09/10 14:00
		1	US-PGPUB;	
		•	ЕРО; ЛРО;	
			DERWENT;	•
			IBM TDB	
	1		חלוז זיזילדו	1

13	0	robot and medium adj10 operartion	USPAT;	2001/09/10 14:01
1		• •	US-PGPUB;	
			ЕРО; ЈРО;	
İ			DERWENT;	
			IBM TDB	
14	4749	robot and medium	USPAT;	2001/09/10 14:01
			US-PGPUB;	
			ЕРО; ЈРО;	
			DERWENT;	
			IBM TDB	
15	8	autonomous and medium and weighting adj coefficient	USPAT;	2001/09/10 14:02
			US-PGPUB;	
			ЕРО; ЈРО;	
			DERWENT;	
			IBM TDB	
16	18	(status adj transition adj chart) or (operational adj state adj model) and	USPAT;	2001/09/10 14:22
		autonomous	US-PGPUB;	
			EPO, JPO,	
			DERWENT;	
			IBM TDB	

model of a physiological process

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4 An agent belief system for multi-agent systems

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5 Linear topological conjugacy of elementary canonical state models three-dimensional auton mous piecewise-linear dynamical systems

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[Abstract] [PDF Full-Text (344 KB)] JNL

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